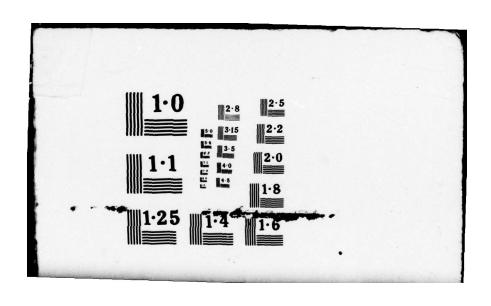
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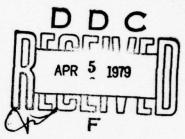
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XU 1313/BQM Serial Nos. 22 & 59

Report No. 5688 February 1968

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NAVAL UNDERSEA WARFARE CENTER

SAN DIEGO, CALIFORNIA 92152

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TRANSDUCER EVALUATION CENTER

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NAVAL UNDERSEA WARFARE CENTER Transducer Calibration Facility San Diego, California 92152

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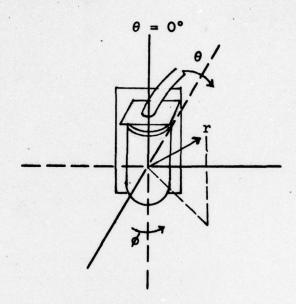
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## TRANSDUCER COORDINATE DIAGRAM



The spherical coordinate system is used to define the angles in the directivity pattern:  $\theta$  and  $\phi$  shown in the above diagram give the directions in which the response is measured. The transducer is placed in the frame of reference with its axis of symmetry coincident with  $\theta = 0^{\circ}$ , its fiducial mark in the  $\phi = 0^{\circ}$  plane, and its center at r = 0.

The two patterns most frequently measured are:

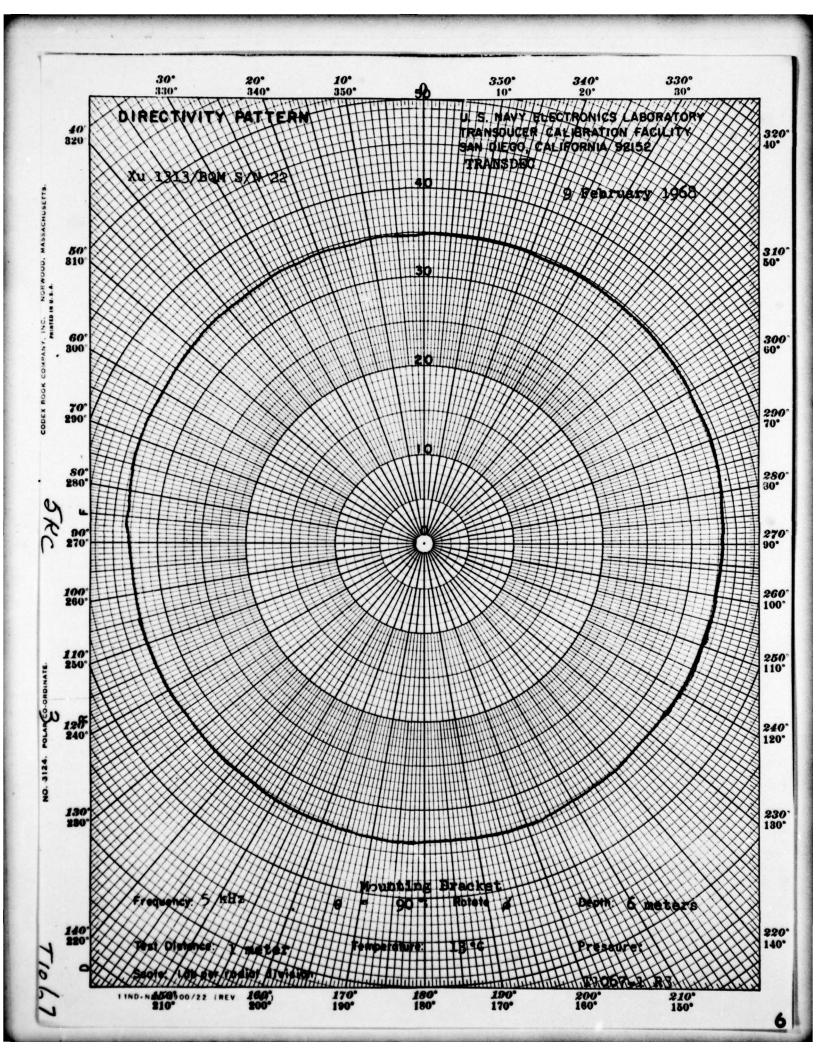
(1) those made by holding \* constant at some angle and rotating θ through 360°.

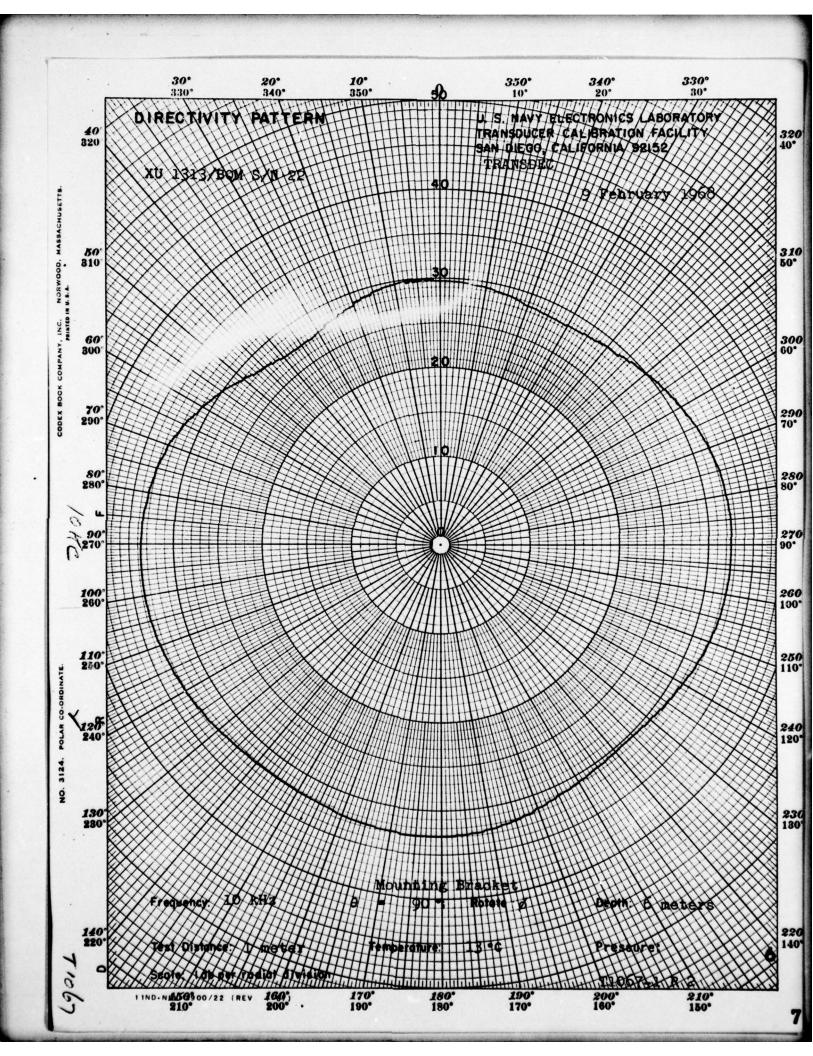
 $( \bullet = a^{\circ} ; rotate \theta )$ 

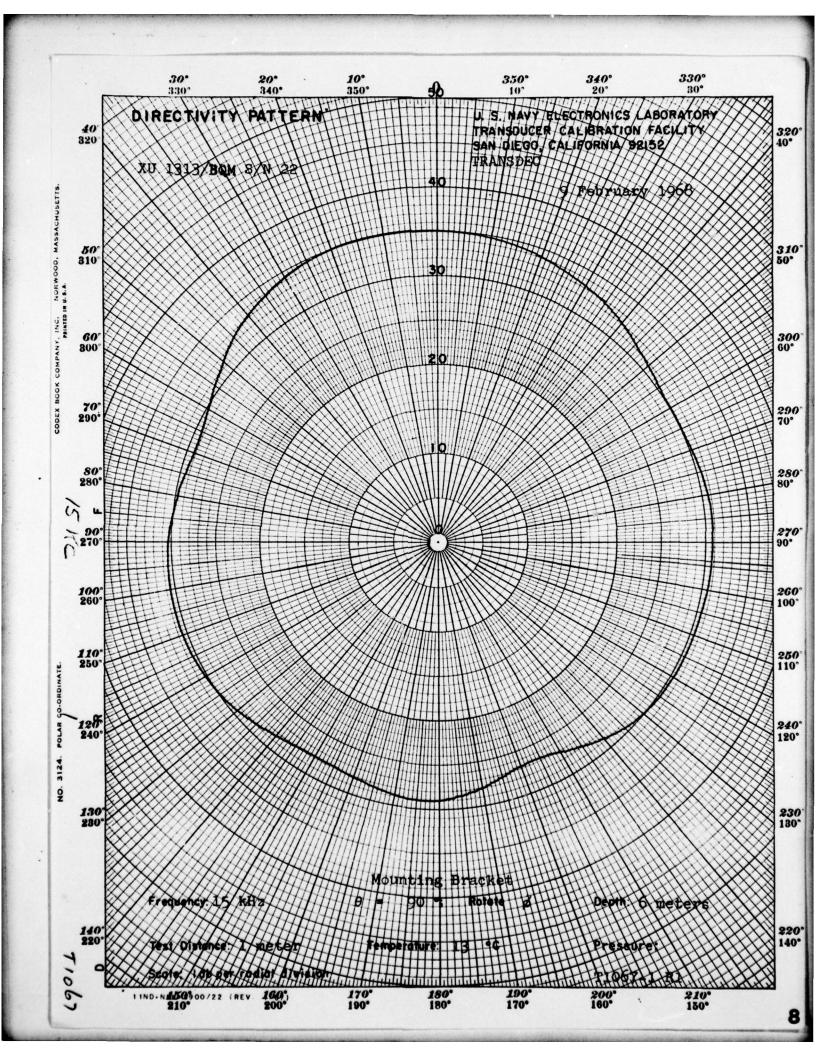
(2) those made by holding  $\theta$  constant at some angle and rotating  $\bullet$  through 360°.

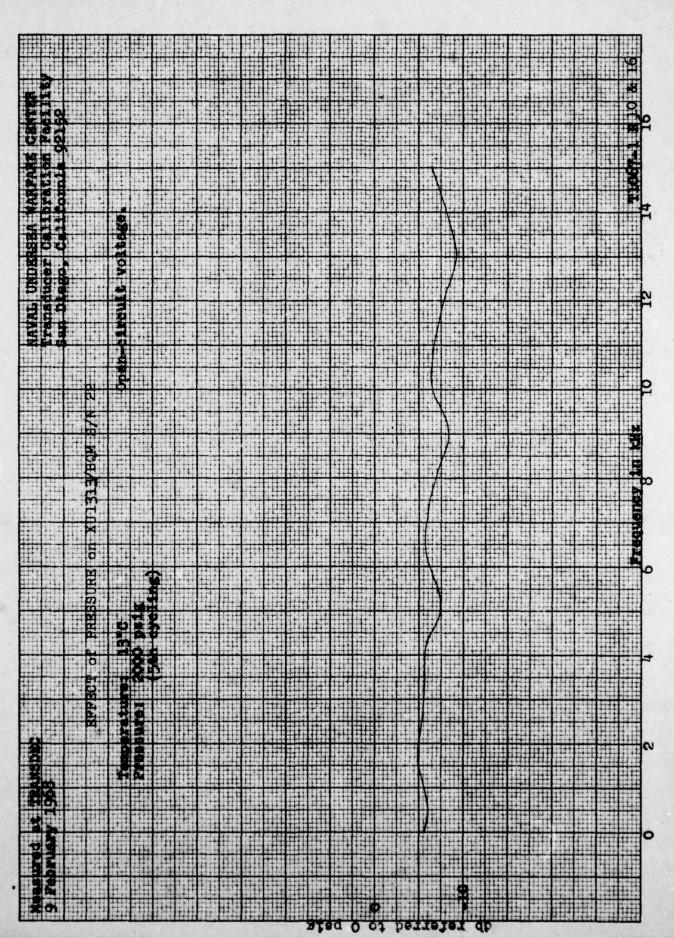
(0 = b°; rotate +)

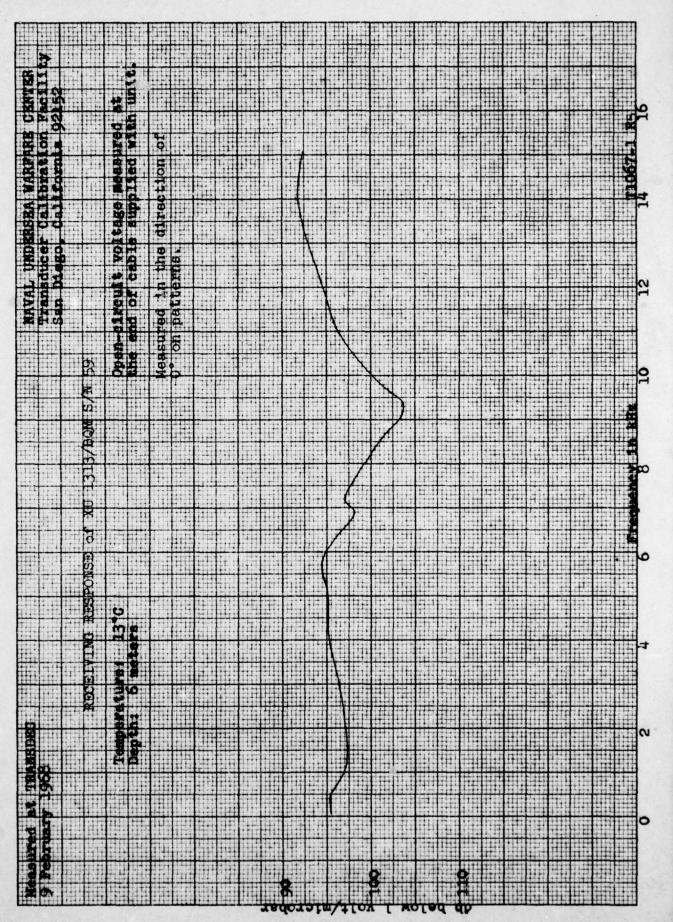
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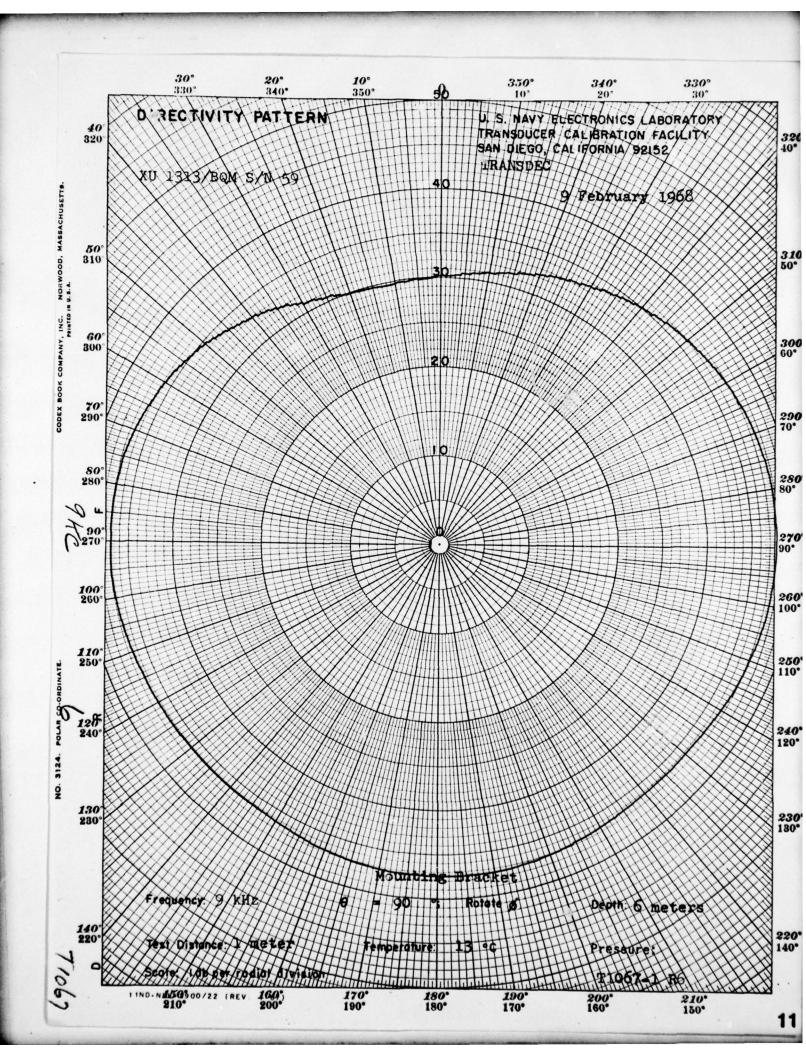


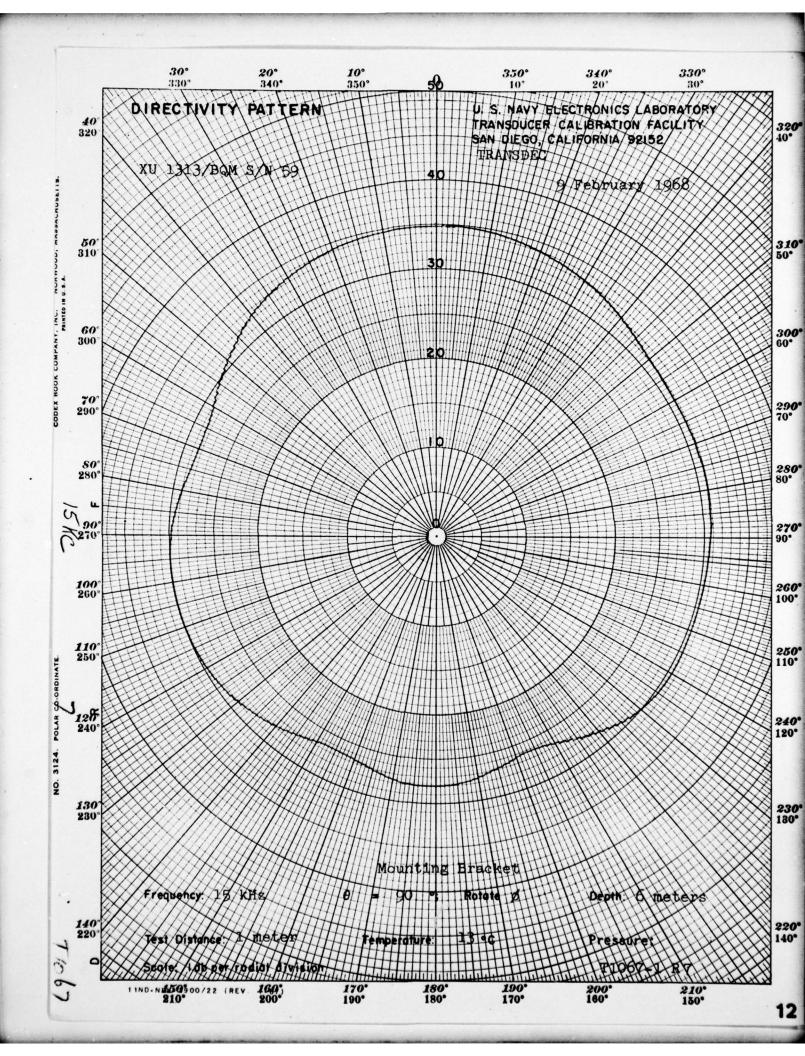


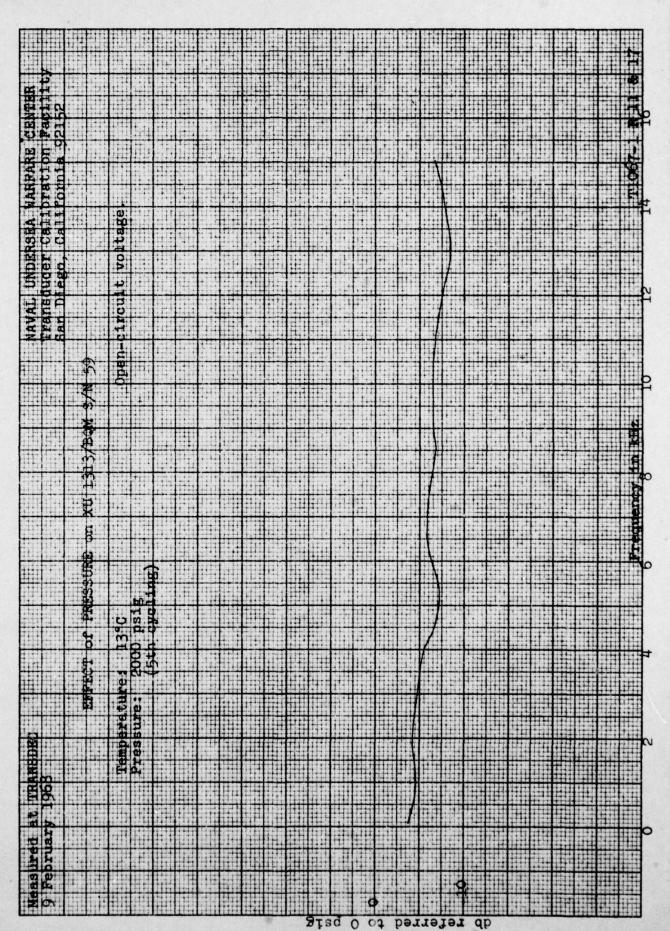


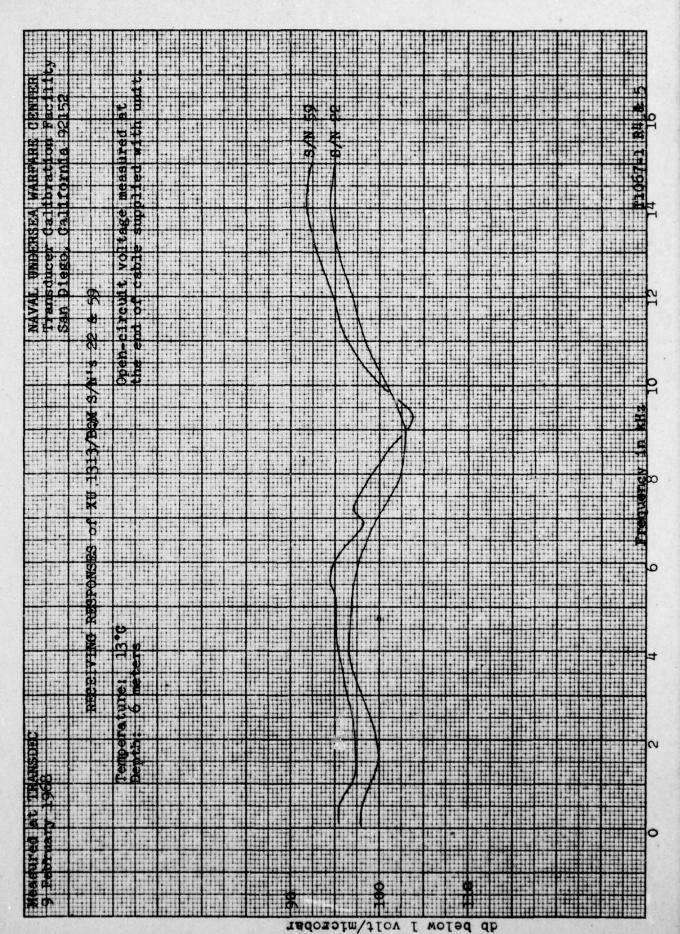












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